## **Autonomous Navigation for Flying Robots**

# Lecture 2.4: Homework Discussion (of last week)

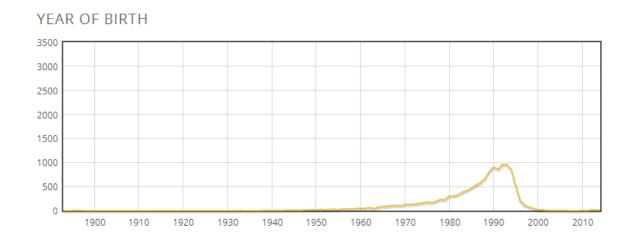
Jürgen Sturm

Technische Universität München

#### **Course Launch**



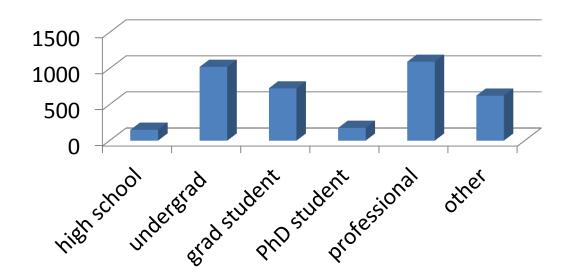
- >15k registrations
- >3k completed first week (videos + exercises)

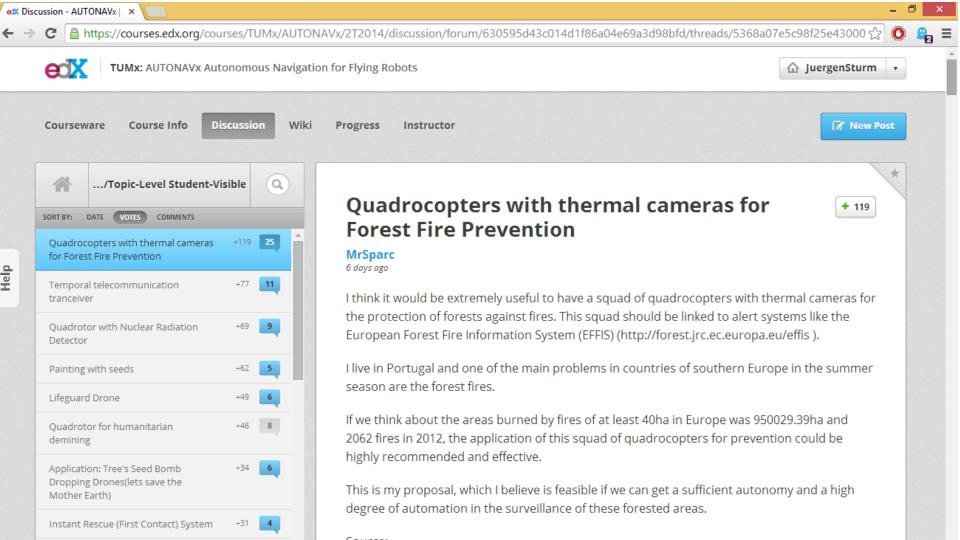


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## **Top Three Applications for Quadrotors**



- Quadrotors with thermal cameras for forest fire prevention [MrSparc, 119 votes]
- Temporal telecommunication tranceiver [npanagia, 77 votes]
- Quadrotor with nuclear radiation detector [detik19, 69 votes]

### **Many Great Ideas**



- Painting with seeds [MarkTillotson, untimonyred 62+34=96 votes]
- Lifeguard drone [chclauson, 49 votes]
- Instant rescue / first contact [Barrtos, 31 votes]
- BeerCopter [AndreasLohr, 29 votes]
- Mosquito Hunter [JasonWang, 27 votes]
- Flying umbrella [LudovicGuegan, 11 votes]
- ...

## **Potentials and Challenges**



- Potentials
  - Completely new applications
  - Mass market bears an enormeous potential
- Challenges
  - Limited battery life
  - Limited payload
  - Safety
  - Legal regulations

#### **Quadrotor Exercises**



- Simulator
  - WebGL
  - Excellent timings
  - Race course exercise upcoming in week 8
- Parrot Ardrone instructions coming soon
  - ROS based
  - Python stub
  - EdX wiki